

# Tractable Computational Methods for Finding Nash Equilibria of Perfect-Information Position Auctions

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How will bidders behave in a position auction that does not meet the assumptions for which theoretical results are known?

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Main message: preliminary, but it works

# Outline

- Auctions & Model
- Action-Graph Games
- Auctions as AGGs
- Computational Experiments
- Economic Experiments

# Types of Position Auctions

- Dimensions:
  - Generalized First Price vs. Generalized Second Price
  - Pay-per-click vs. Pay-per-impression
  - Weighted vs. Unweighted:
    - “Effective Bid”:  $\text{bid} * \text{weight}$
    - Ads ranked by effective bid
    - Payment:  $\text{effective bid} / \text{weight}$
- Current Usage (Google, Microsoft, Yahoo!):
  - Weighted, Per-Click, GSP

# Model of Auction Setting

Full-information, one-shot game [Varian, 2007; Edelman, Ostrovsky, Schwarz, 2006 (“EOS”)]

	Weights	CTR across positions	CTR across bidders	Value per Click	Bid Amounts
[EOS]	Always 1	Decreasing	Constant	One value per bidder	Continuous
[Varian]	Arbitrary	Decreasing	Proportional to Weight (“Separable”)	One value per bidder	Continuous
Our model	Arbitrary	Arbitrary	Arbitrary	Arbitrary	Discrete

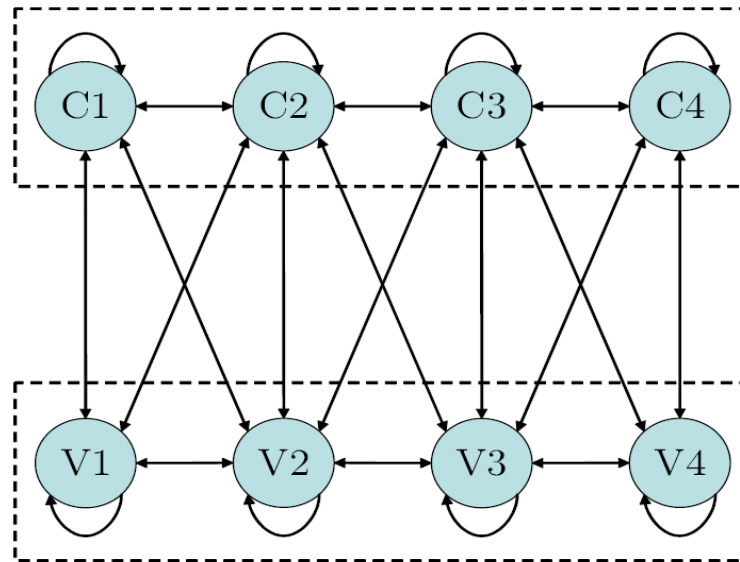


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- Auctions & Model
- **Action-Graph Games**
- Auctions as AGGs
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# What are AGGs?

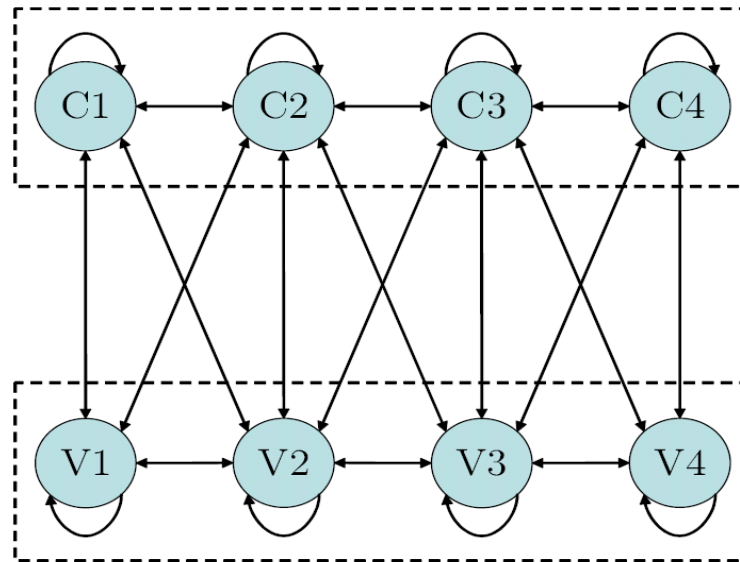
- Action Graphs:
  - Each node represents an action.
  - Arcs indicate payoff dependencies.



- [Bhat & Leyton-Brown, 2004; Jiang & Leyton-Brown, 2006]

# What are AGGs?

- Action Graphs:
  - Each node represents an action.
  - Arcs indicate payoff dependencies.
  - “Function Nodes” increase sparsity.



- [Bhat & Leyton-Brown, 2004; Jiang & Leyton-Brown, 2006]

# Why Use AGGs? [Bhat & Leyton-Brown, 2004]

- Small: Compact representation of a one-shot, full-information game
  - Frequently polynomial in  $n$

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- Small: Compact representation of a one-shot, full-information game
  - Frequently polynomial in  $n$
- Fast: Dynamic programming can compute expected utility in  $\sim O(an^{i+1})$  [Jiang & Leyton-Brown, 2006]
  - Plug into existing equilibrium solvers (e.g. simplicial subdivision [van der Laan, Talman, and van Der Heyden, 1987] or GNM [Govindan, Wilson, 2003]) for exponential speedup

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# Weighted GFP as AGG

Agent A

$\beta=2$

Agent B

$\beta=2$

Agent C

$\beta=3$

# Weighted GFP as AGG

Effective  
Bid ( $e_i$ )

0

2

3

4

6

8

9

10

Agent A  
 $\beta=2$

0

1

2

3

4

5

Agent B  
 $\beta=2$

0

1

2

3

4

5

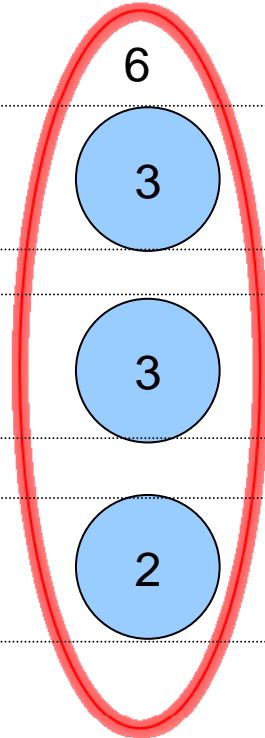
Agent C  
 $\beta=3$

0

1

2

3





# Weighted GFP as AGG

Effective

Bid ( $e_i$ )

0

2

3

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6

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9

10

Agent A

$\beta=2$

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1

2

3

4

5

Agent B

$\beta=2$

0

1

2

3

4

5

Agent C

$\beta=3$

0

1

2

3

#

$e_i=0$

#

$e_i=2$

#

$e_i=3$

#

$e_i=4$

#

$e_i=6$

#

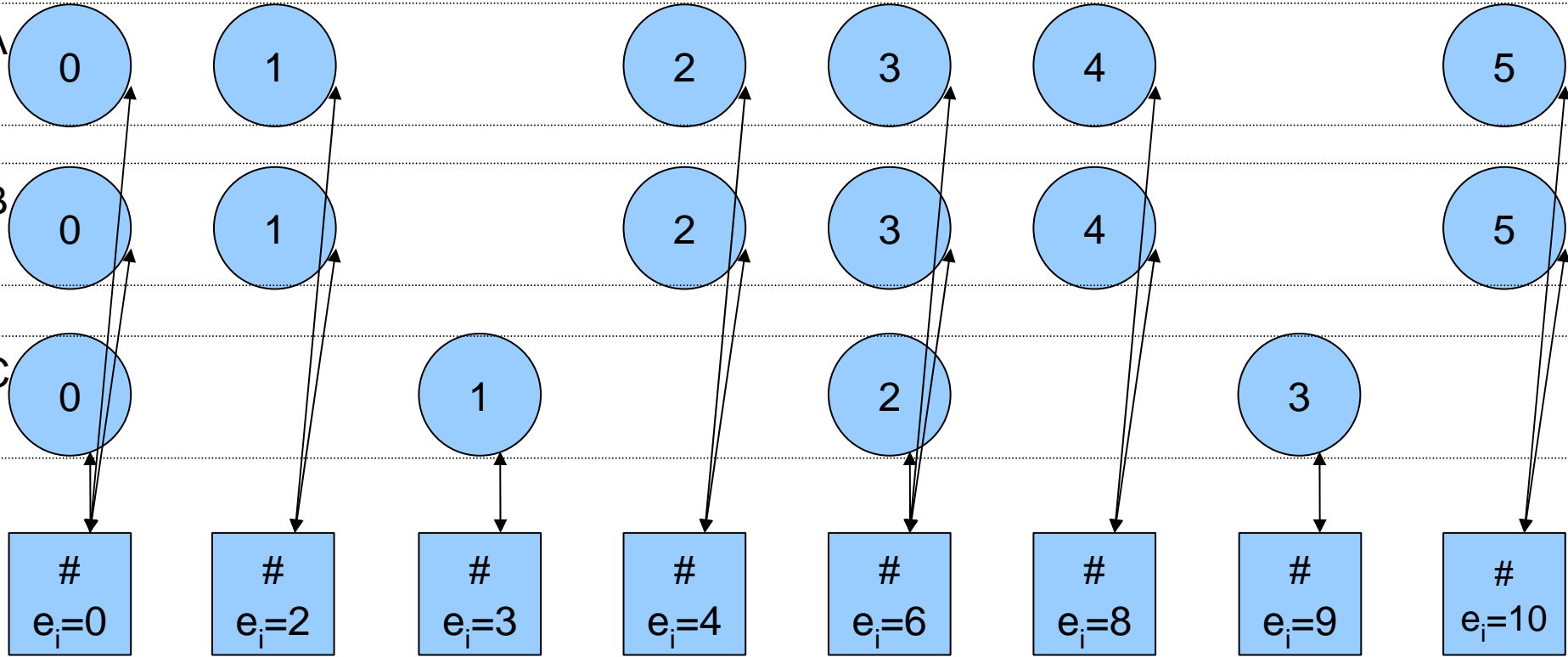
$e_i=8$

#

$e_i=9$

#

$e_i=10$



# Weighted GFP as AGG

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Bid ( $e_i$ )

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Agent C

$\beta=3$

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1

2

3

#  
 $e_i=0$

#  
 $e_i=2$

#  
 $e_i=3$

#  
 $e_i=4$

#  
 $e_i=6$

#  
 $e_i=8$

#  
 $e_i=9$

#  
 $e_i=10$

#  
 $e_i \geq 0$

#  
 $e_i \geq 2$

#  
 $e_i \geq 3$

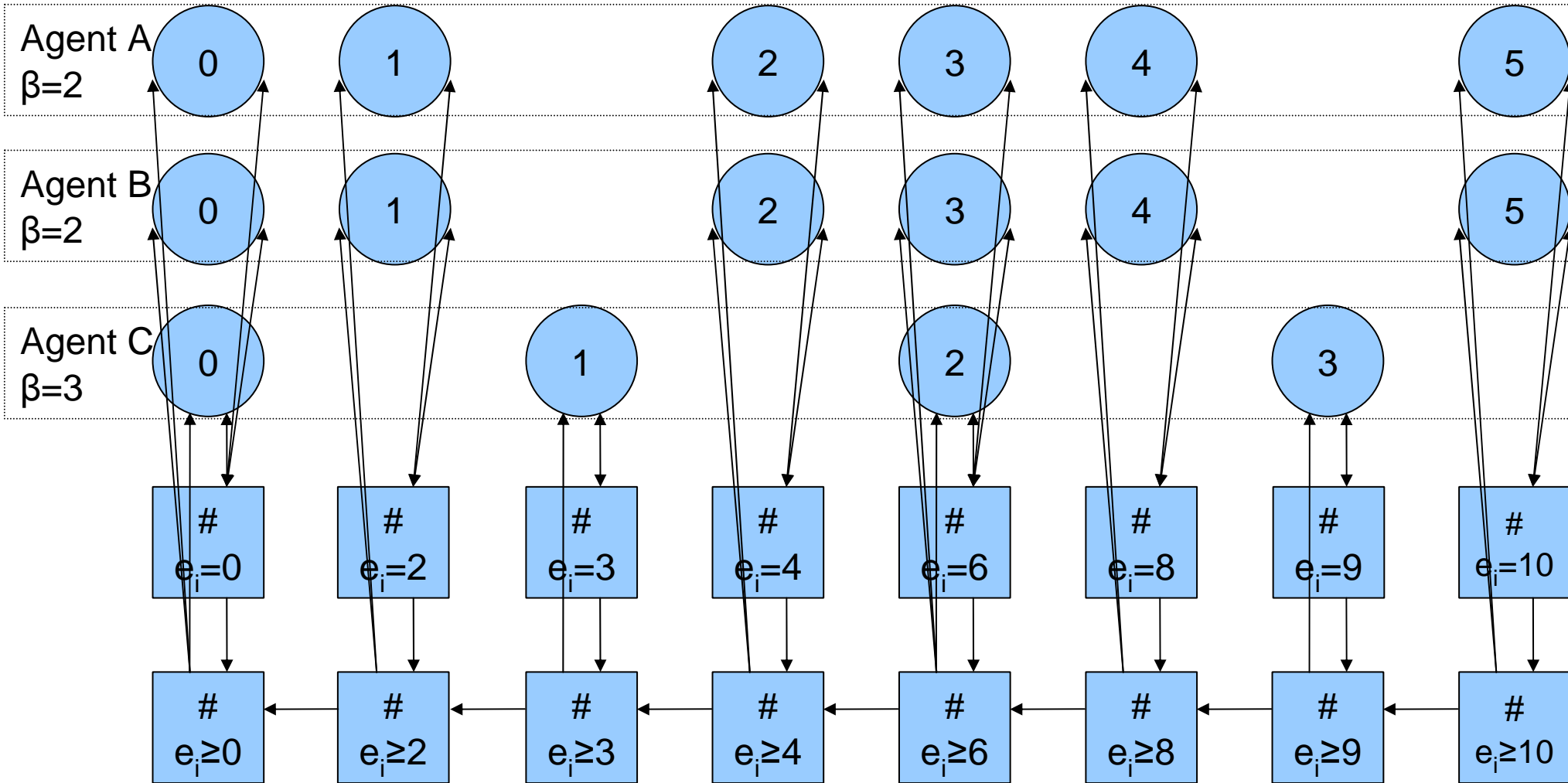
#  
 $e_i \geq 4$

#  
 $e_i \geq 6$

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# Weighted GFP as AGG

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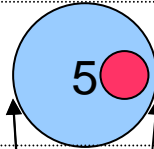
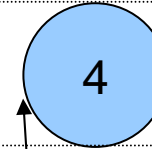
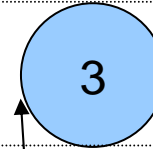
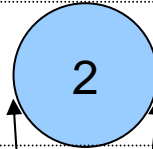
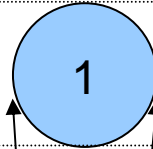
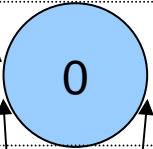
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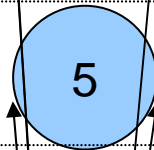
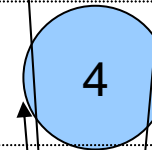
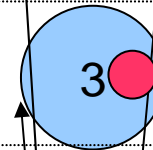
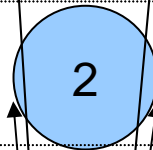
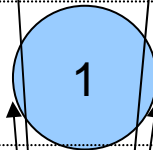
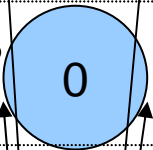
Agent A

$\beta=2$



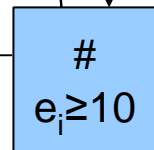
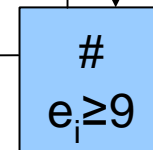
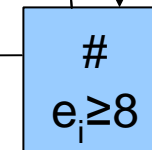
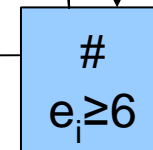
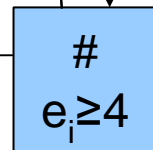
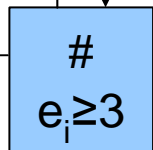
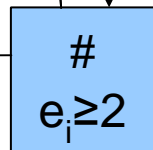
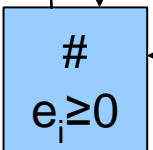
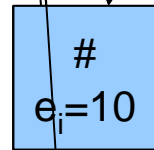
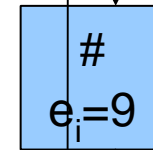
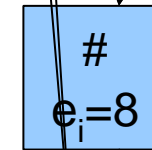
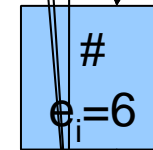
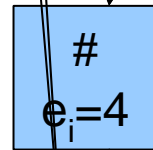
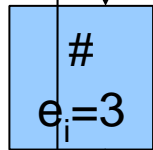
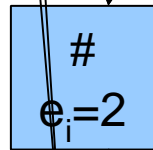
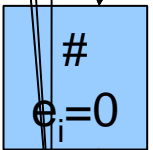
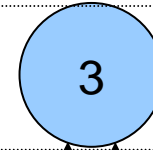
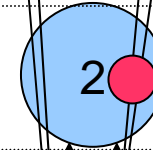
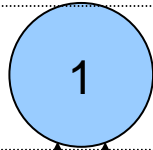
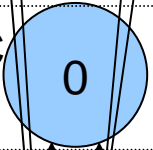
Agent B

$\beta=2$



Agent C

$\beta=3$



# Weighted GFP as AGG

Effective

Bid ( $e_i$ )

0

2

3

4

6

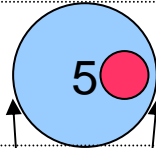
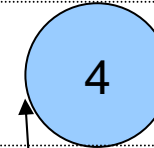
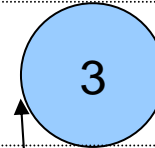
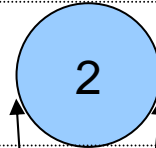
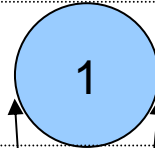
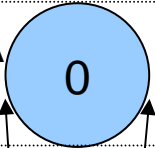
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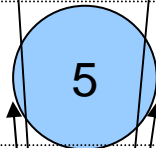
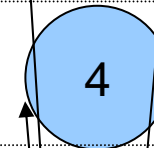
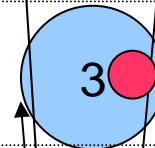
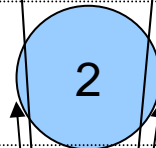
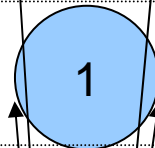
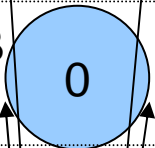
Agent A

$\beta=2$



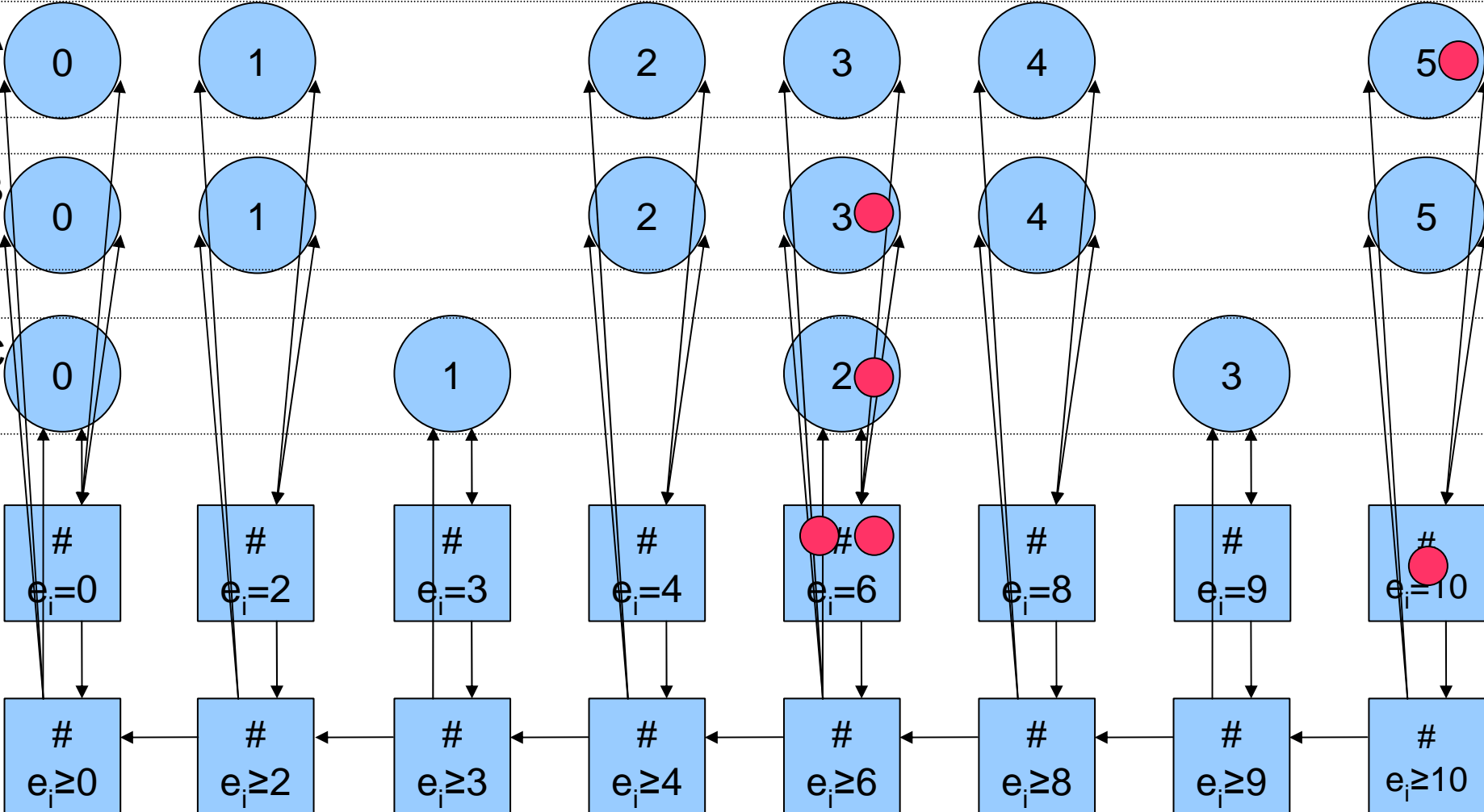
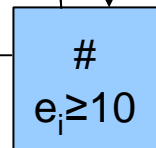
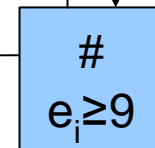
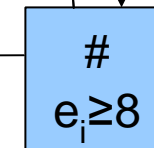
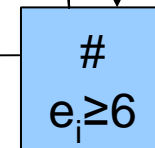
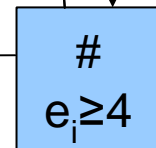
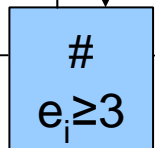
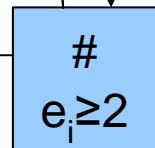
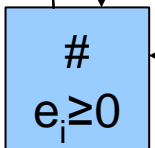
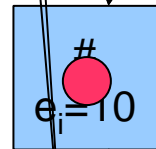
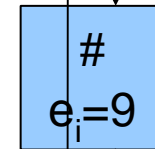
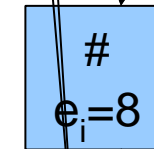
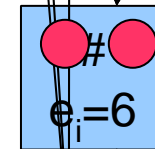
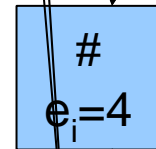
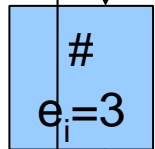
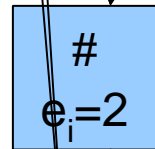
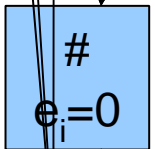
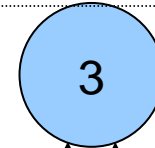
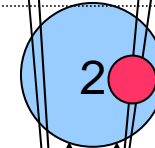
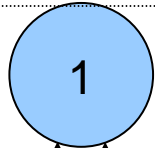
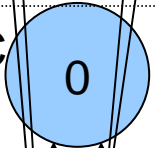
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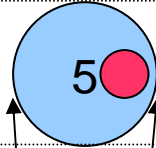
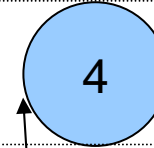
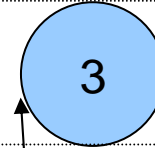
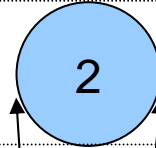
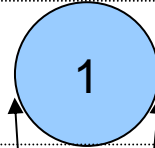
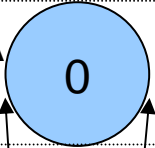
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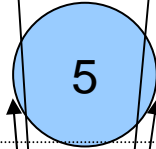
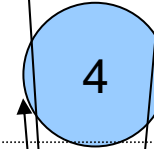
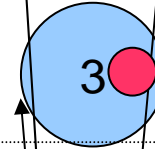
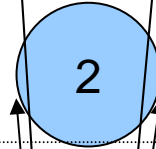
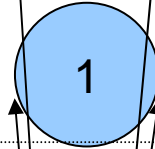
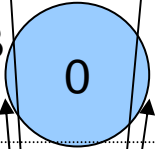
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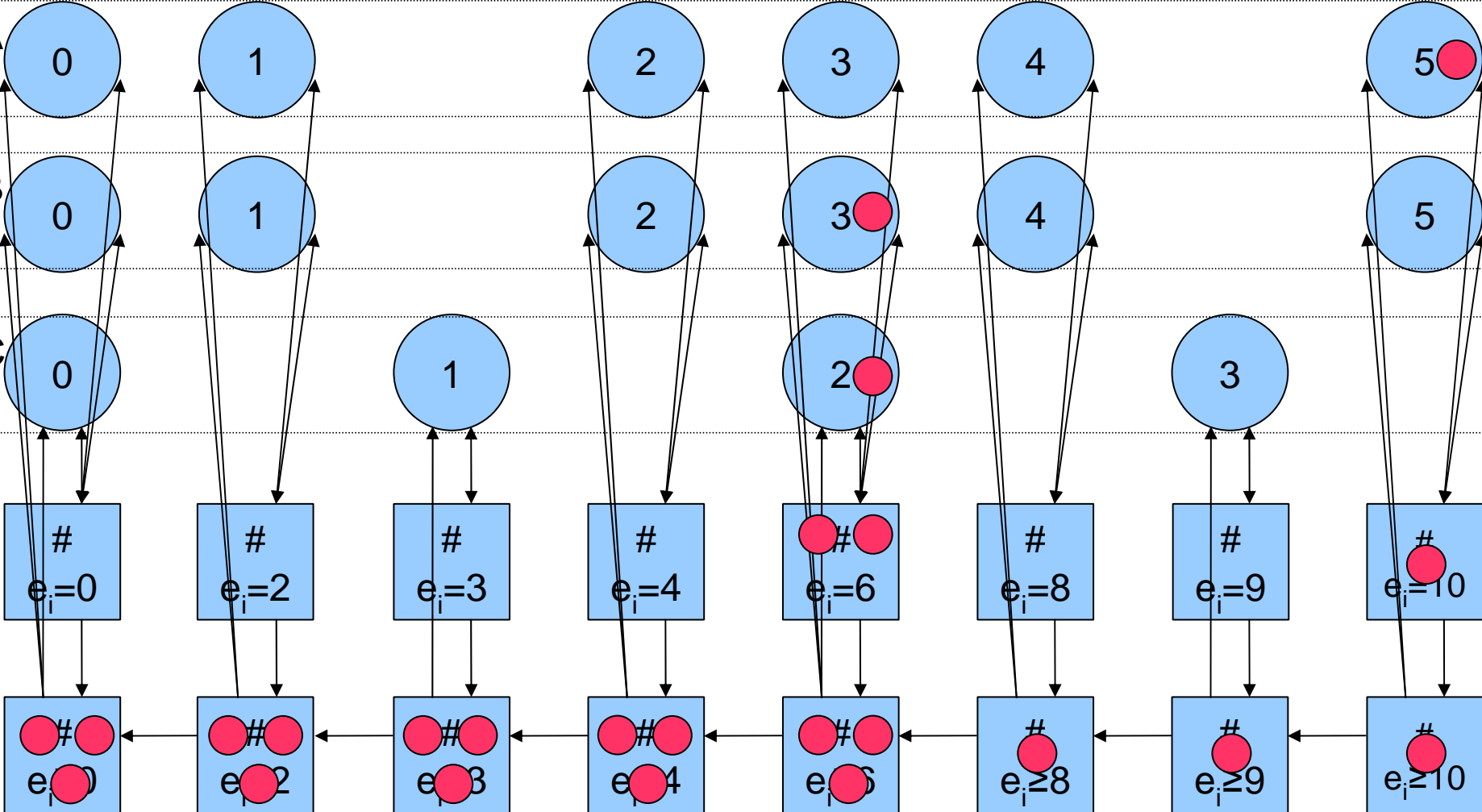
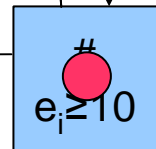
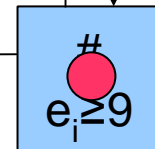
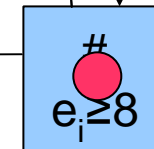
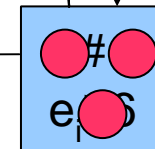
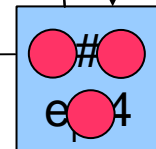
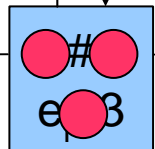
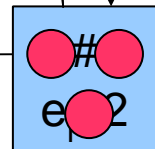
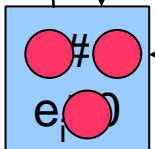
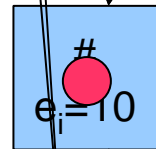
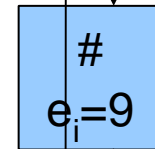
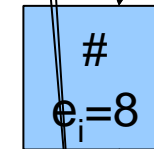
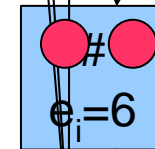
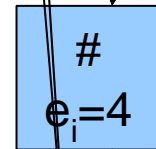
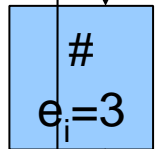
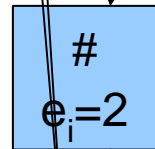
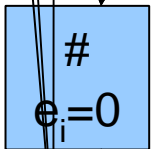
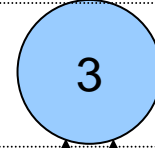
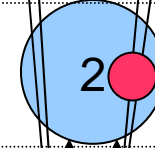
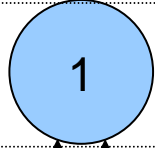
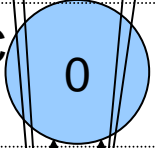
Agent A  
 $\beta=2$



Agent B  
 $\beta=2$



Agent C  
 $\beta=3$



# Weighted GFP as AGG

Effective Bid ( $e_i$ )

0

2

3

4

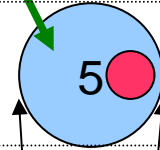
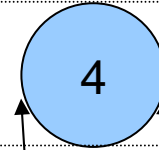
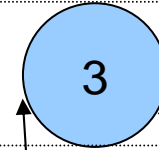
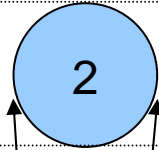
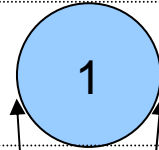
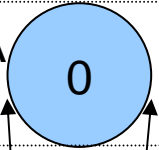
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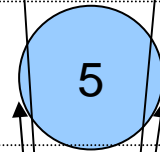
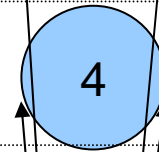
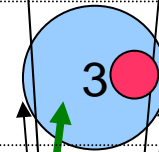
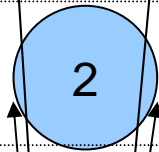
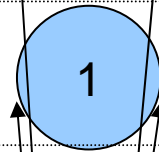
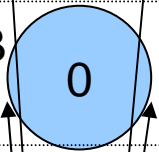
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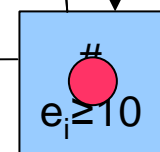
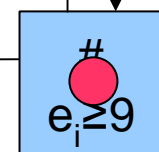
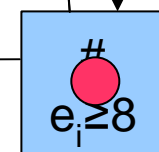
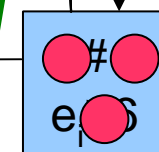
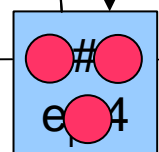
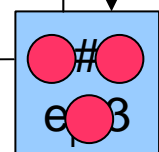
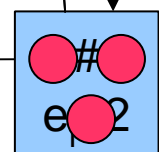
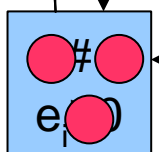
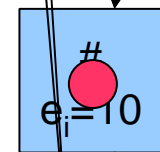
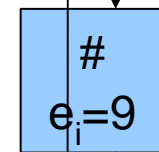
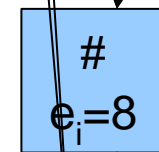
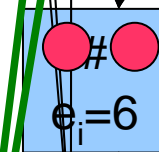
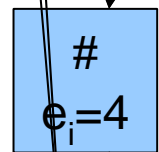
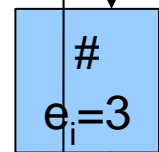
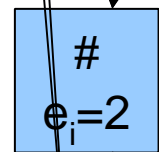
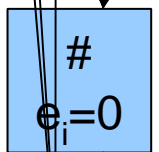
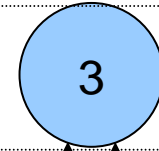
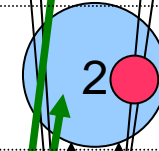
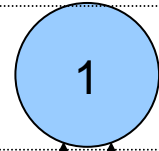
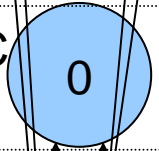
Agent A  
 $\beta=2$



Agent B  
 $\beta=2$



Agent C  
 $\beta=3$



Position = 1



Position = 2,3

(Ties broken randomly)

# Representing GSP

- Start from a GFP graph
  - same method of computing a bidder's position
- We need to add new nodes to compute prices

# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

2

3

4

6

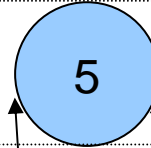
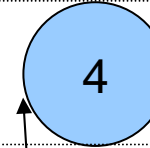
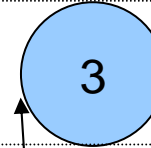
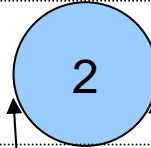
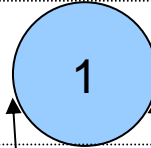
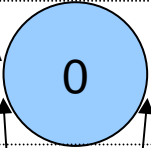
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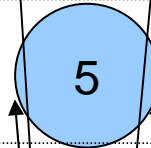
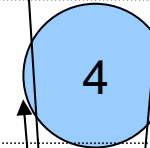
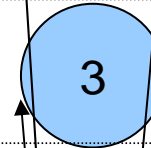
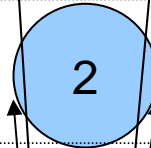
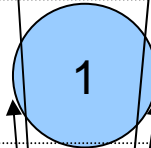
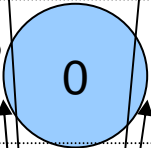
Agent A

$\beta=2$



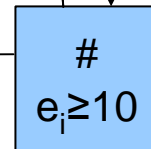
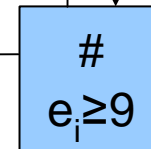
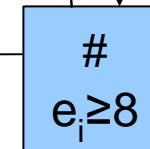
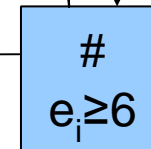
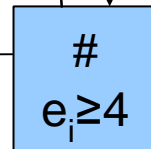
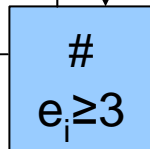
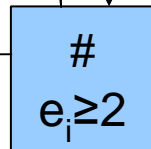
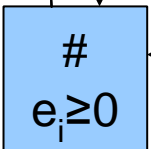
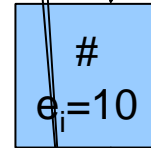
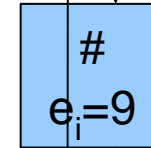
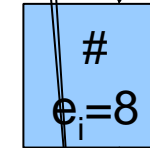
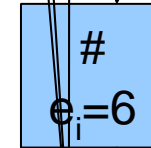
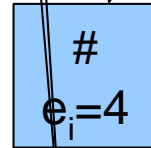
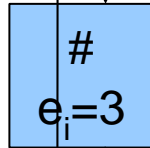
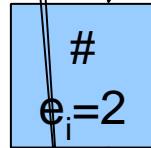
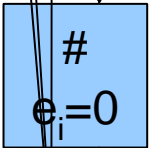
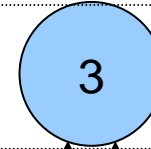
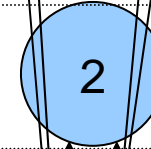
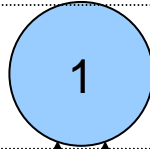
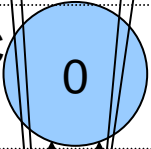
Agent B

$\beta=2$



Agent C

$\beta=3$





# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

2

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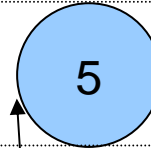
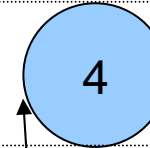
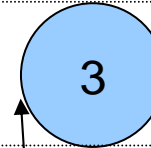
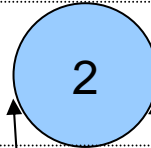
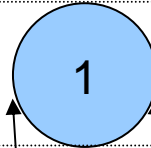
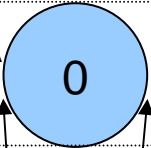
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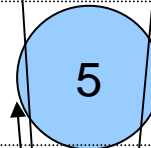
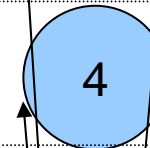
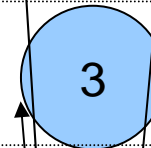
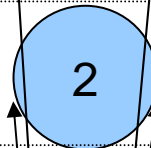
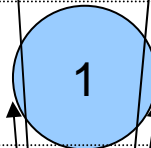
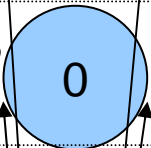
Agent A

$\beta=2$



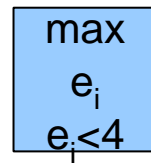
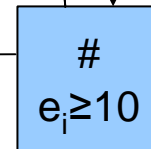
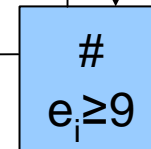
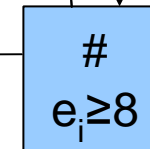
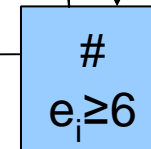
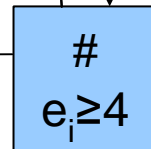
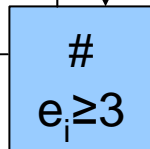
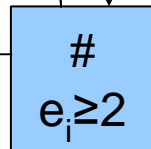
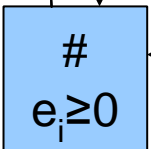
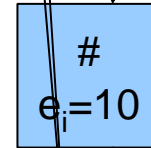
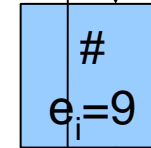
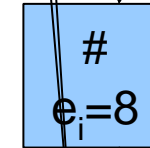
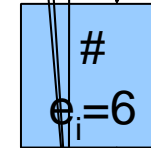
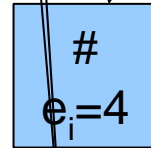
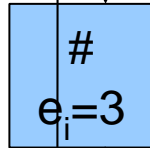
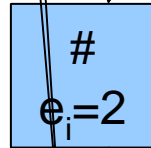
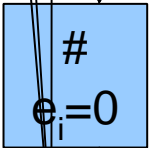
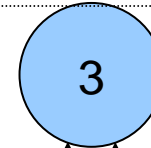
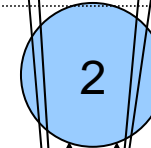
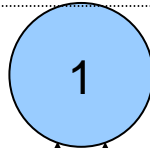
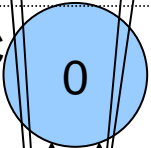
Agent B

$\beta=2$



Agent C

$\beta=3$



# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

2

3

4

6

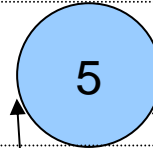
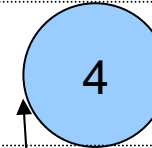
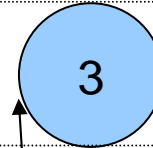
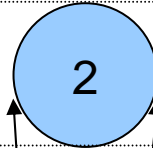
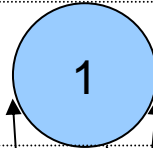
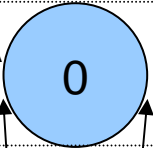
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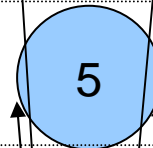
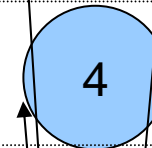
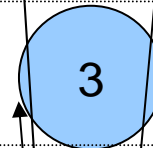
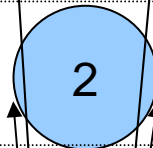
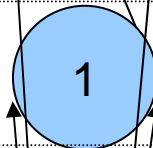
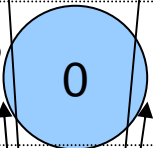
Agent A

$\beta=2$



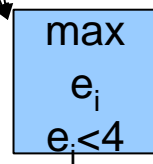
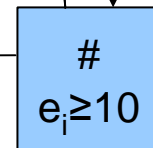
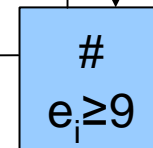
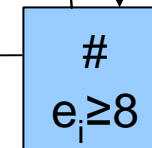
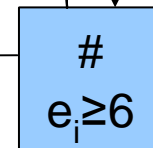
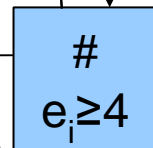
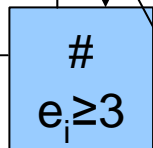
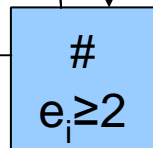
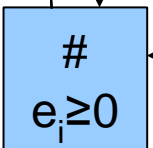
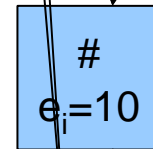
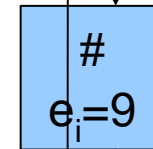
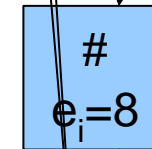
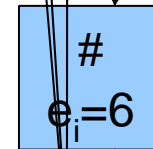
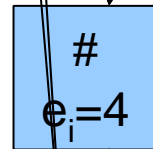
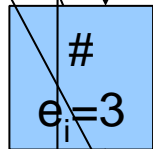
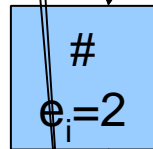
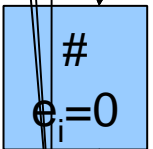
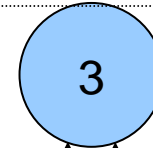
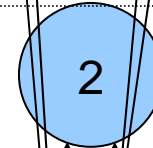
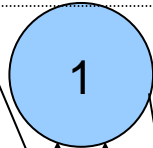
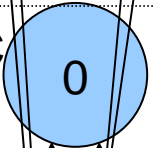
Agent B

$\beta=2$



Agent C

$\beta=3$



# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

2

3

4

6

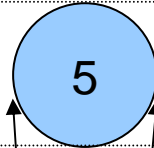
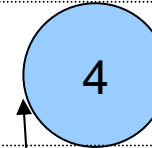
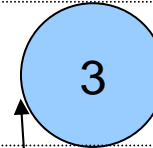
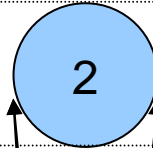
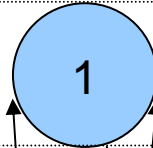
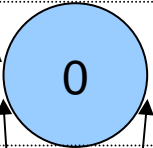
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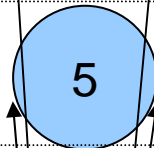
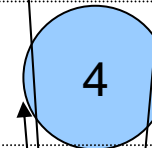
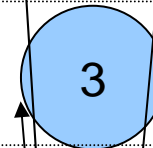
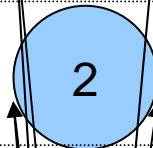
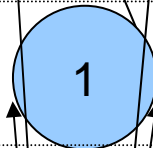
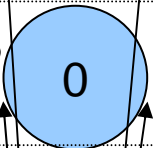
Agent A

$\beta=2$



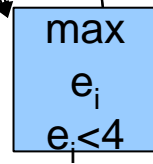
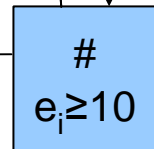
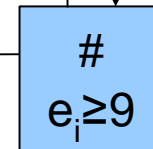
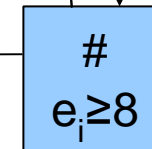
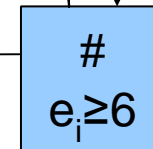
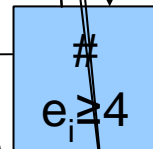
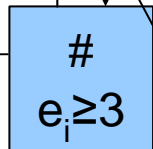
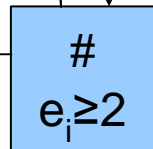
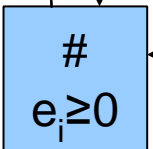
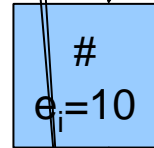
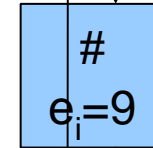
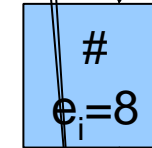
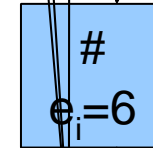
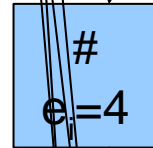
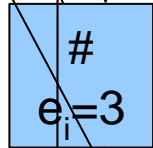
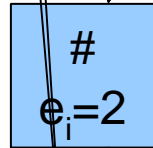
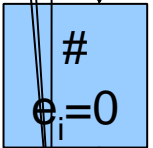
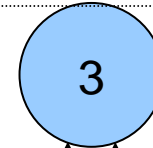
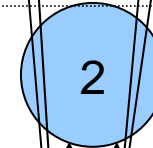
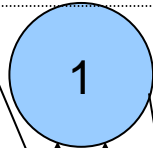
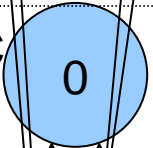
Agent B

$\beta=2$



Agent C

$\beta=3$



# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

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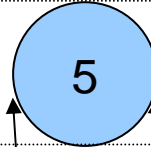
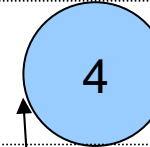
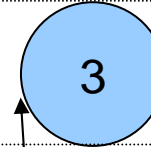
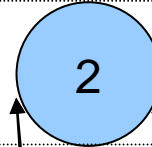
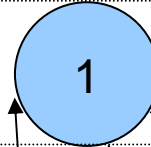
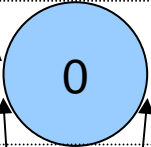
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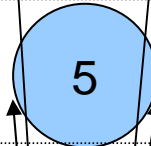
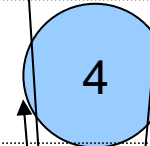
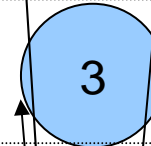
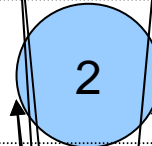
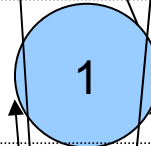
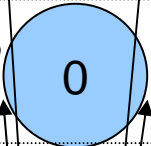
Agent A

$\beta=2$



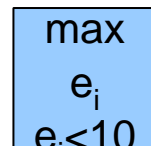
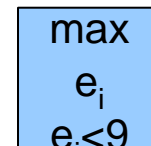
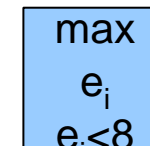
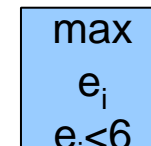
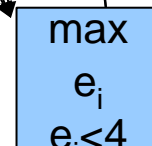
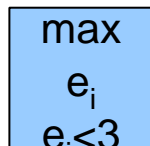
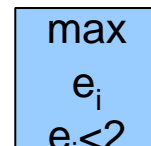
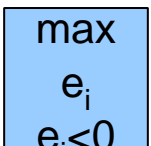
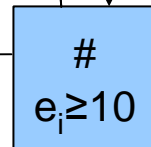
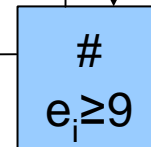
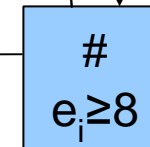
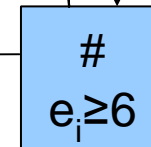
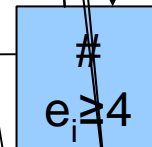
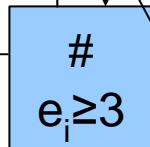
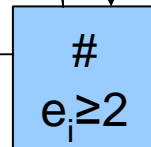
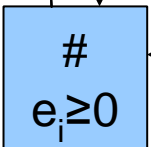
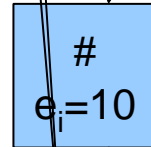
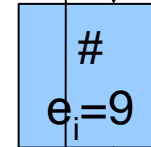
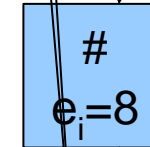
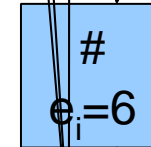
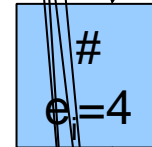
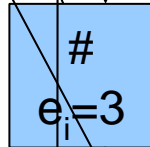
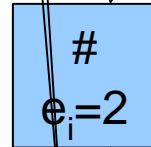
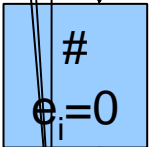
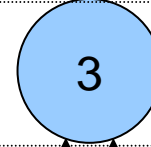
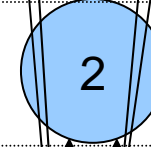
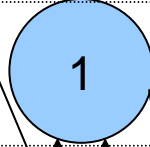
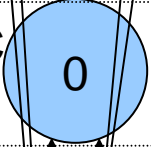
Agent B

$\beta=2$



Agent C

$\beta=3$



# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

2

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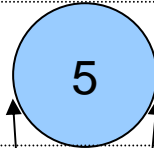
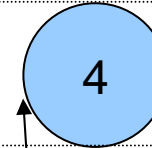
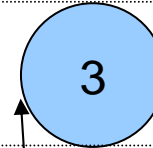
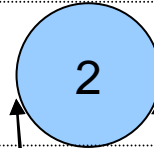
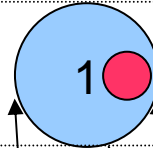
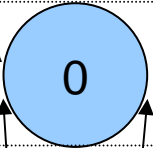
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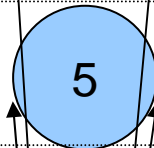
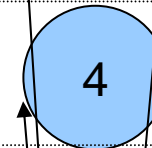
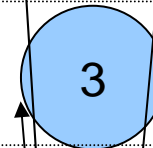
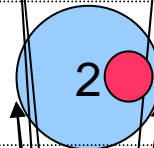
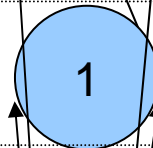
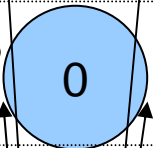
Agent A

$\beta=2$



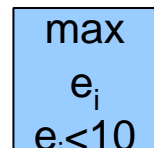
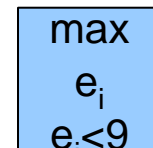
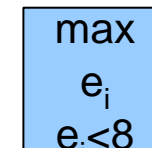
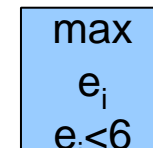
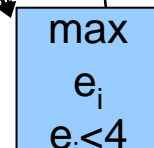
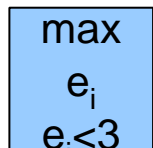
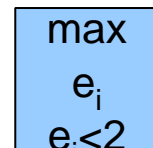
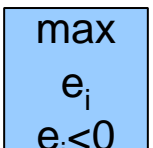
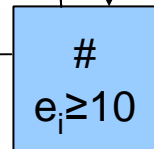
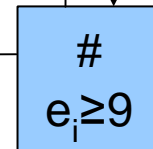
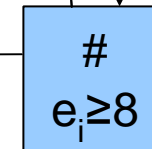
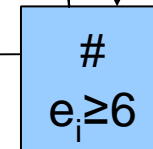
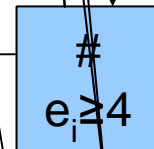
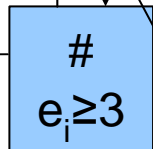
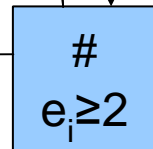
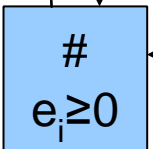
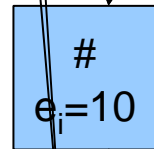
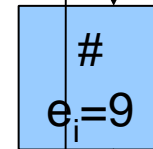
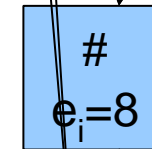
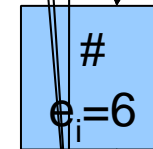
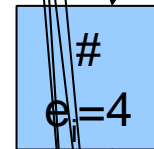
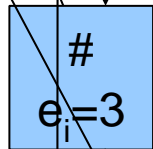
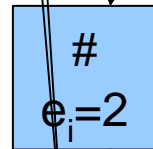
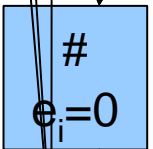
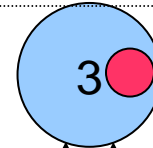
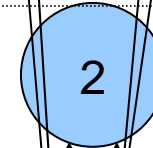
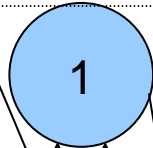
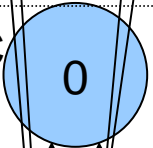
Agent B

$\beta=2$



Agent C

$\beta=3$



# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

2

3

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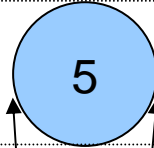
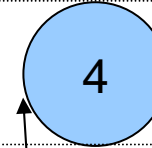
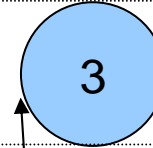
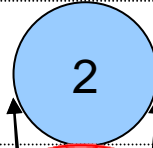
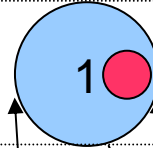
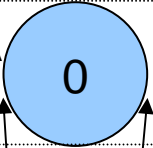
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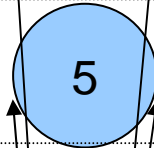
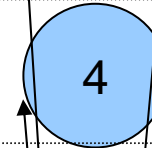
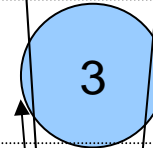
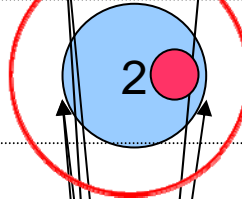
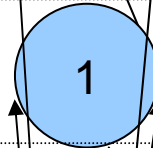
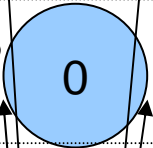
Agent A

$\beta=2$



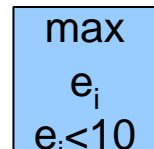
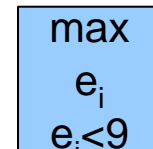
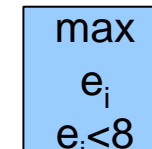
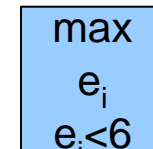
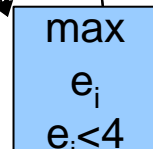
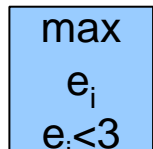
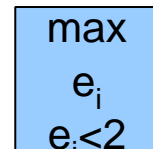
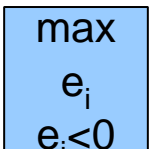
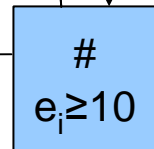
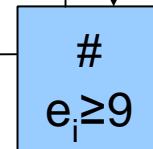
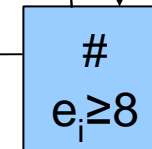
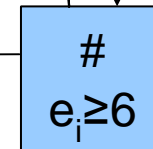
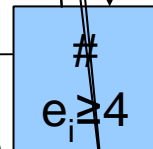
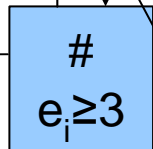
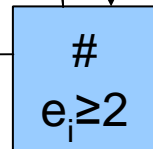
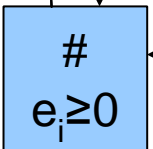
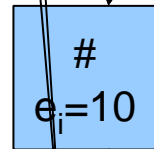
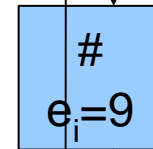
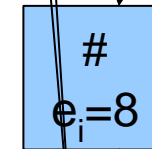
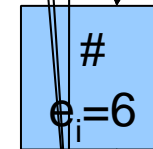
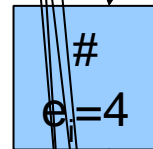
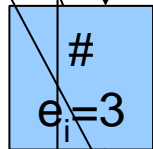
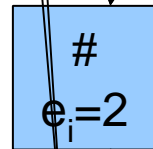
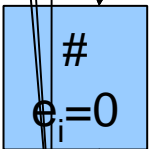
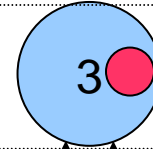
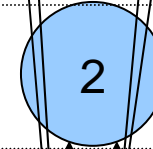
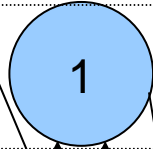
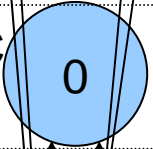
Agent B

$\beta=2$



Agent C

$\beta=3$



# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

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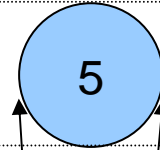
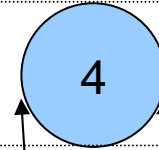
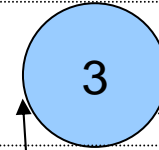
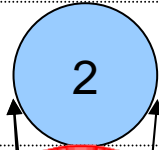
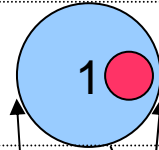
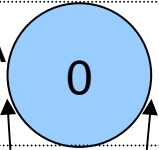
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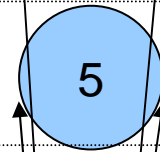
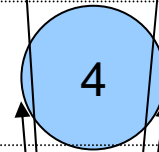
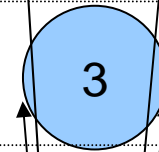
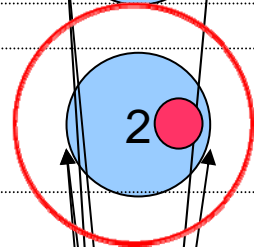
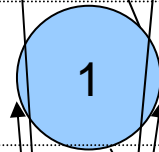
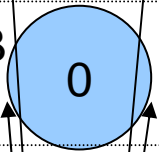
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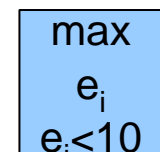
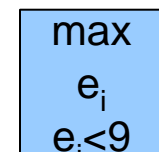
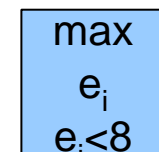
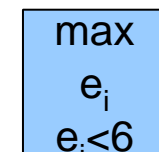
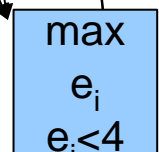
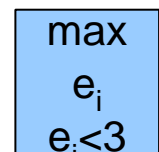
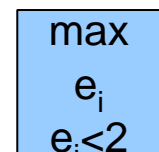
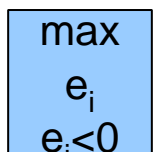
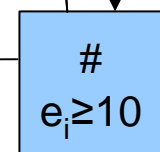
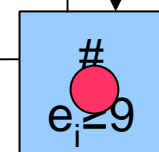
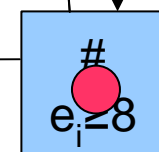
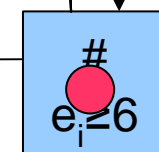
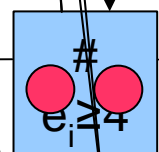
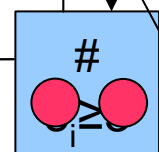
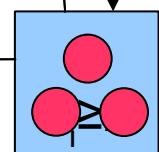
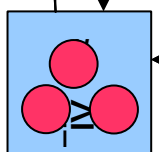
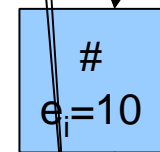
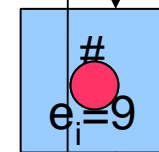
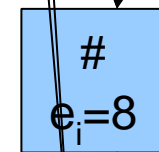
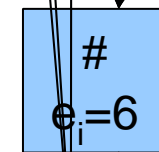
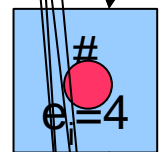
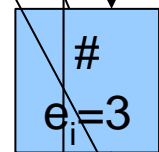
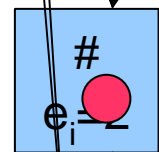
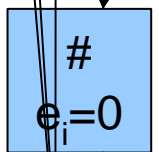
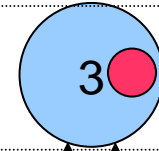
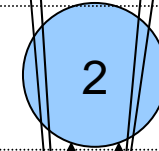
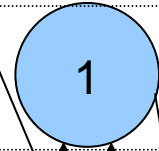
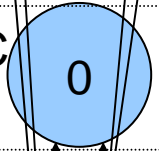
Agent A  
 $\beta=2$



Agent B  
 $\beta=2$



Agent C  
 $\beta=3$



# Weighted GSP as AGG

Effective

Bid ( $e_i$ )

0

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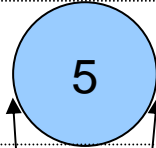
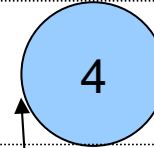
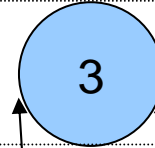
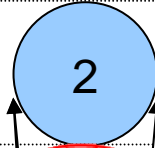
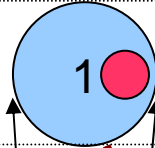
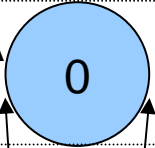
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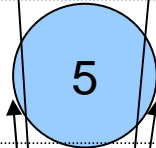
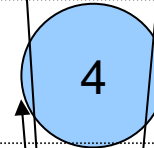
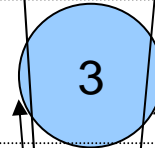
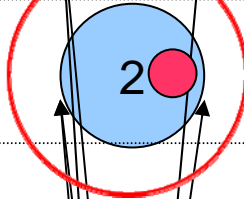
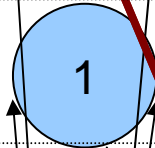
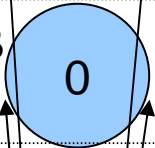
Agent A

$\beta=2$



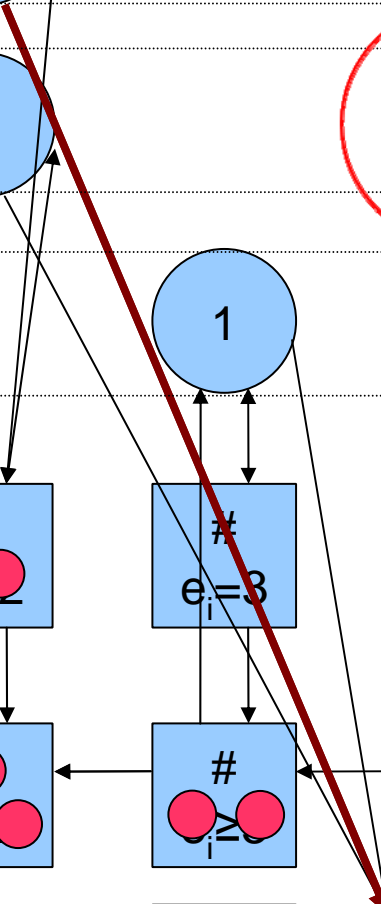
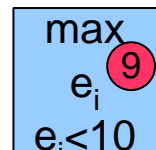
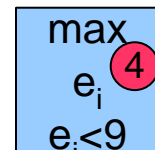
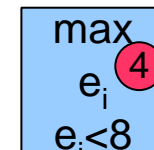
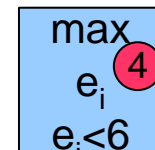
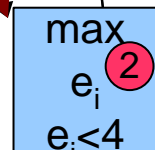
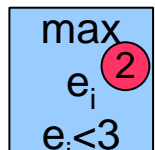
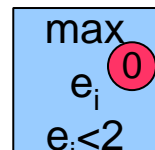
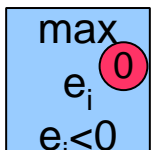
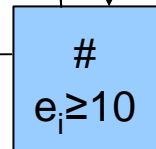
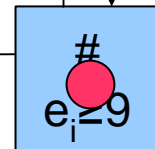
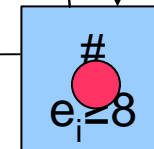
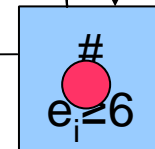
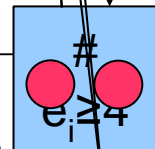
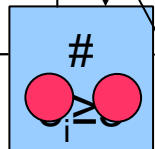
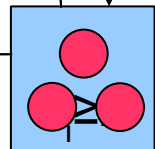
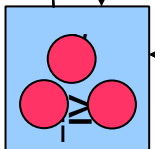
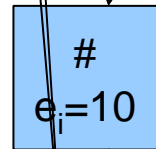
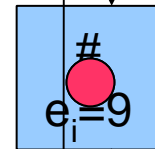
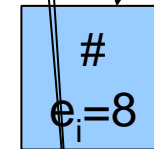
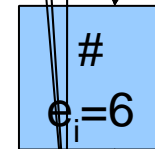
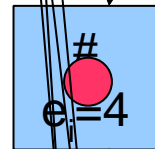
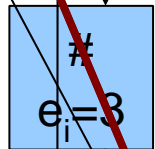
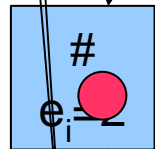
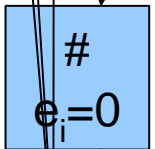
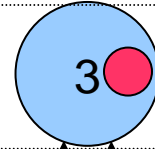
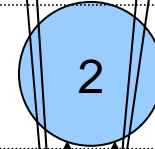
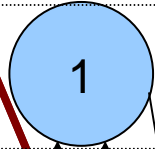
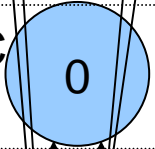
Agent B

$\beta=2$



Agent C

$\beta=3$





# Weighted GSP as AGG

Position = 2  
Price =  $2/\beta=1$

Effective

Bid ( $e_i$ )

0

2

3

4

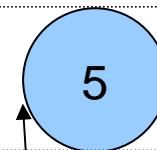
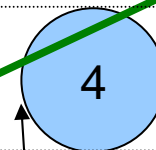
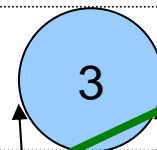
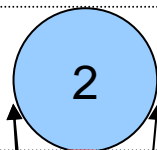
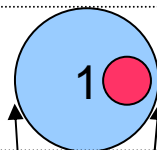
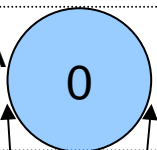
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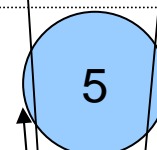
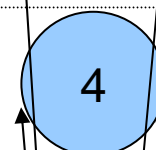
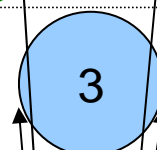
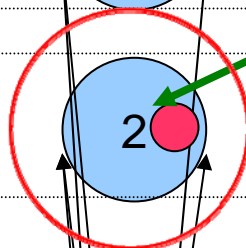
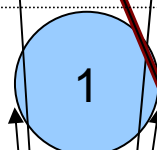
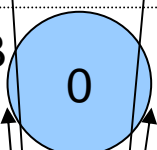
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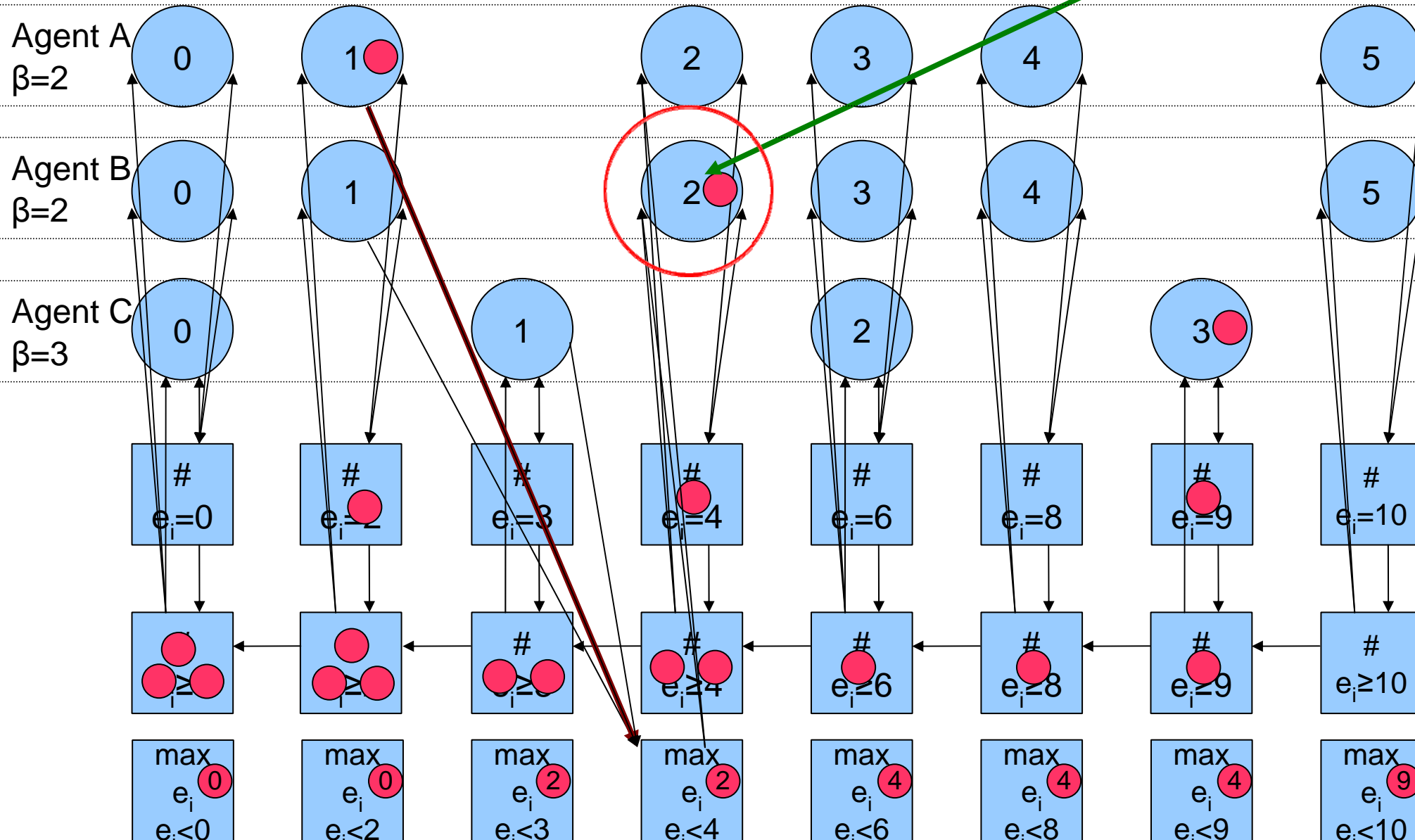
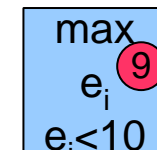
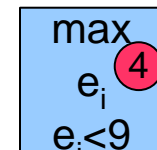
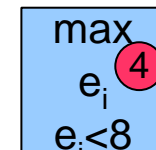
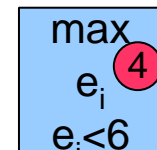
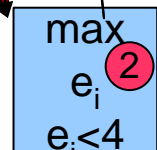
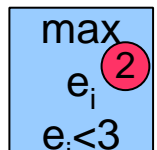
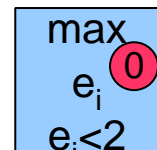
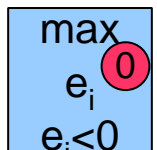
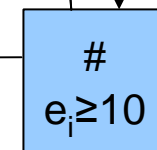
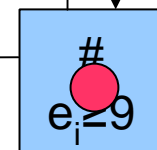
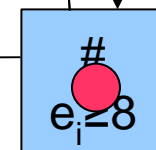
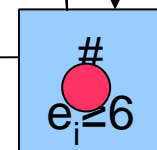
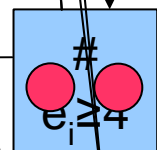
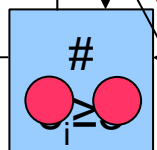
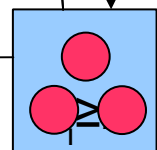
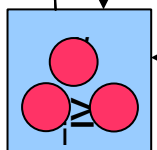
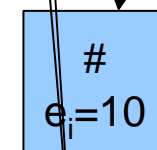
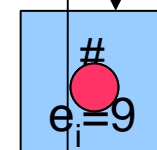
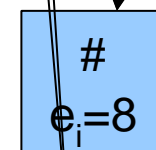
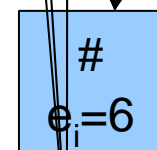
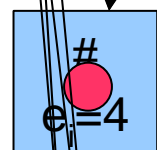
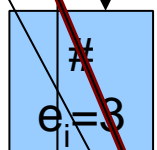
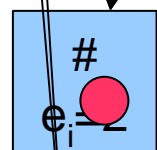
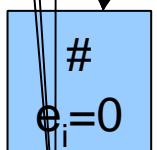
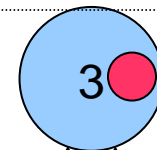
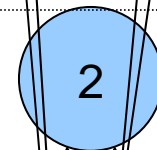
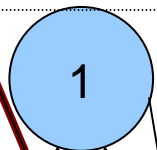
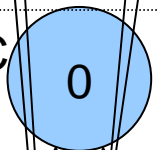
Agent A  
 $\beta=2$



Agent B  
 $\beta=2$



Agent C  
 $\beta=3$



# Outline

- Auctions & Model
- Action-Graph Games
- Auctions as AGGs
- **Computational Experiments**
- Economic Experiments

# Model of Auction Setting

	<b>Weights</b>	<b>CTR across positions</b>	<b>CTR across bidders</b>	<b>Value per Click</b>	<b>Bid Amounts</b>
<b>[EOS]</b>	Always 1	Decreasing	Constant	One value per bidder	Continuous
<b>[Varian]</b>	Arbitrary	Decreasing	Proportional to Weight ("Separable")	One value per bidder	Continuous
<b>Our model</b>	Arbitrary	Arbitrary	Arbitrary	Arbitrary	Discrete

# Model of Auction Setting

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Our model	Arbitrary	Arbitrary	Arbitrary	Arbitrary	Discrete

# Why Instantiate [Varian]?

- Validate by comparing with Varian's analytical results for weighted, pay-per-click GSP
  - and obtain computational results on a model of independent interest
- Obtain novel economic results
  - “Apples-to-apples” comparison: how do different auctions perform given identical preferences?
- Most appropriate model is still an open question

# Model of Auction Setting

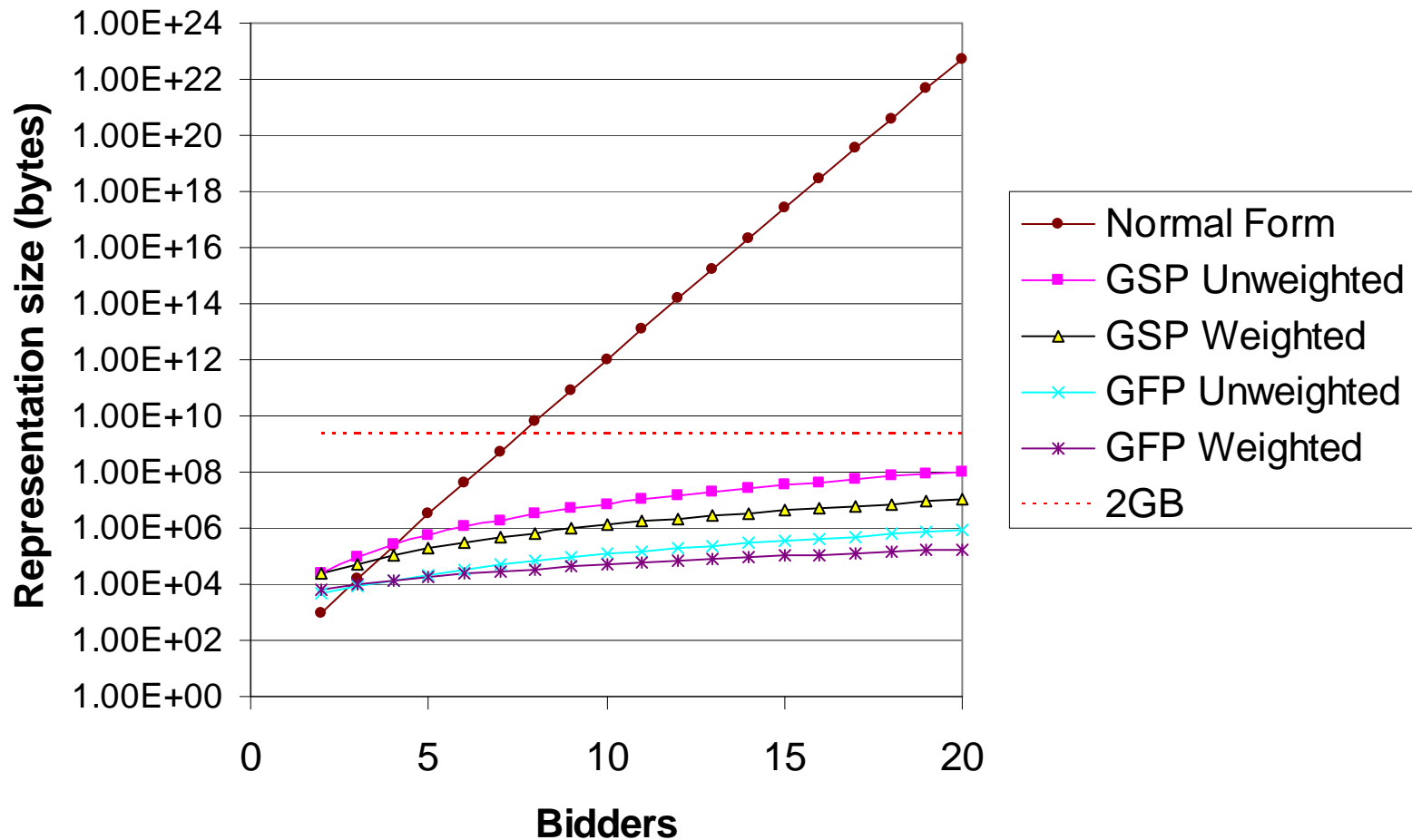
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<b>[EOS]</b>	Always 1	Decreasing	Constant	One value per bidder	Continuous
<b>[Varian]</b>	Arbitrary	Decreasing	Proportional to Weight ("Separable")	One value per bidder	Continuous
<b>Our model</b>	Arbitrary	Arbitrary	Arbitrary	Arbitrary	Discrete
<b>Problem Distribution</b>	Uniform[0,1]	Uniform[0,1] * CTR of higher slot	Proportional to Weight ("Separable")	One value per bidder: Uniform[0,1]	Discrete

# Experimental Setup

- 10 bidders, 5 slots
- Integer bids between 0 and 10
- For pay-per-click, normalize value/click:
  - Scale  $\max_i \text{value}_i$  to 10, then scale other values proportionately
    - to use full range of discrete bid amounts
- For pay-per-impression, normalize value/impression.

# Size Experiments: Players

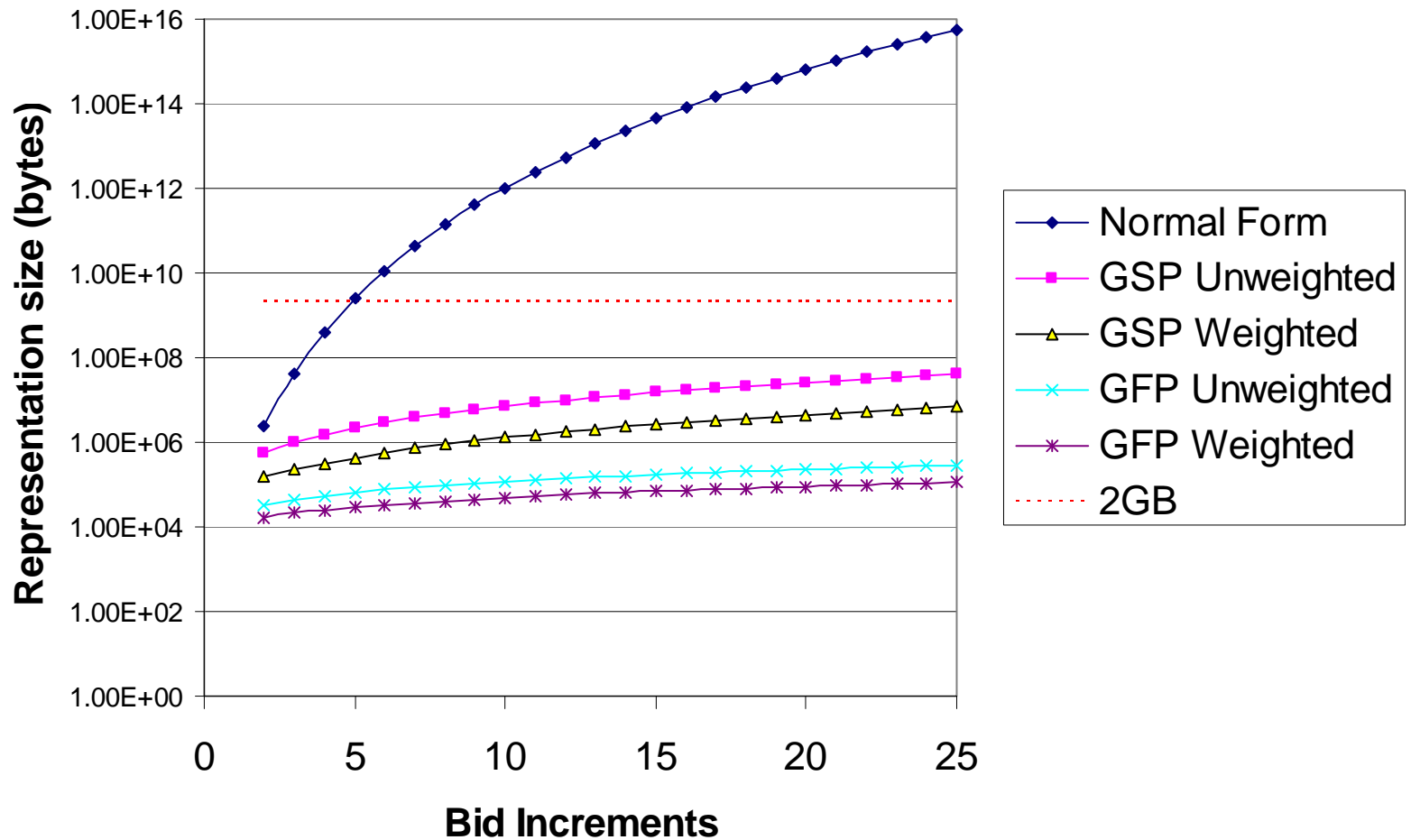
Integer bids: 0 to 10





# Size Experiments: Bid Increments

## 10 bidders

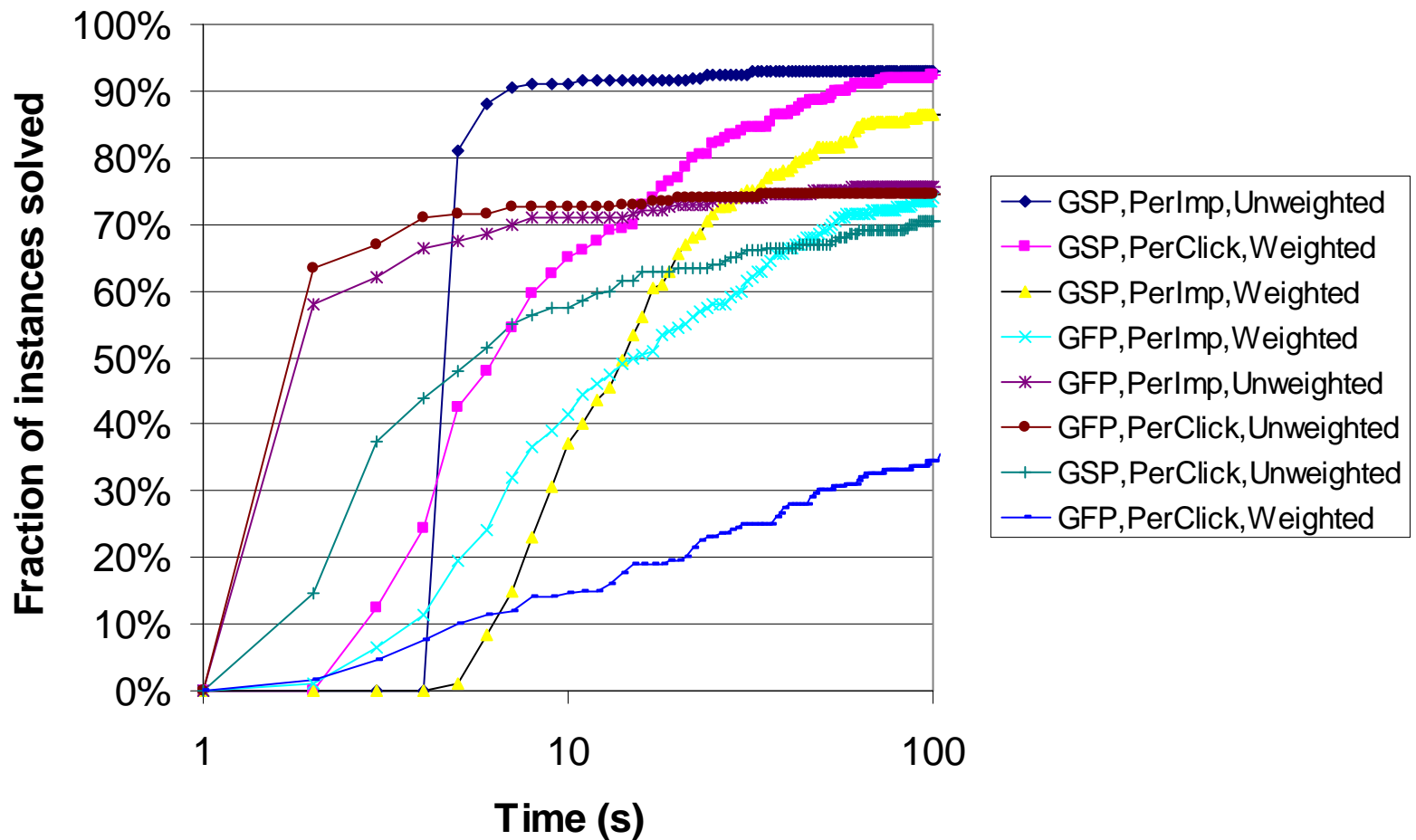


# Runtime Experiments: Test-bed

- Environment:
  - Intel Xeon 3.2GHz, 2MB cache, 2GB RAM
  - Suse Linux 10.1
- Solver software:
  - Gambit [McKelvey, McLennan, Turocy, 2007] implementation of simplicial subdivision “simpdiv” [van der Laan, Talman, and van Der Heyden, 1987], AGG-specific dynamic programming inner loop<sup>1</sup> [Jiang & Leyton-Brown, 2006]

1. <http://www.cs.ubc.ca/~jiang/agg/>

# Runtime Experiments: Results



\* much longer experiments are ongoing...

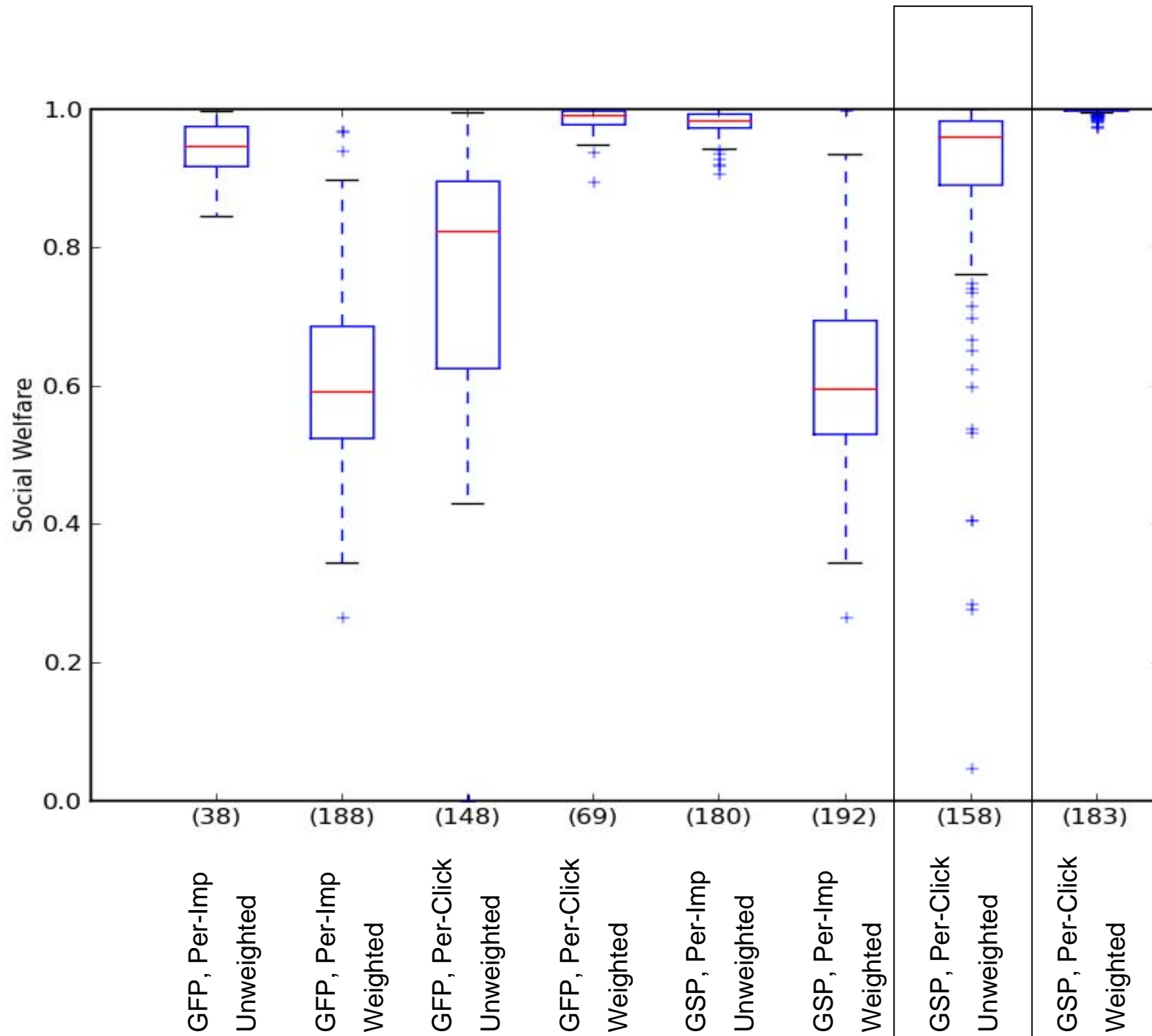
# Outline

- Auctions & Model
- Action-Graph Games
- Auctions as AGGs
- Computational Experiments
- **Economic Experiments**

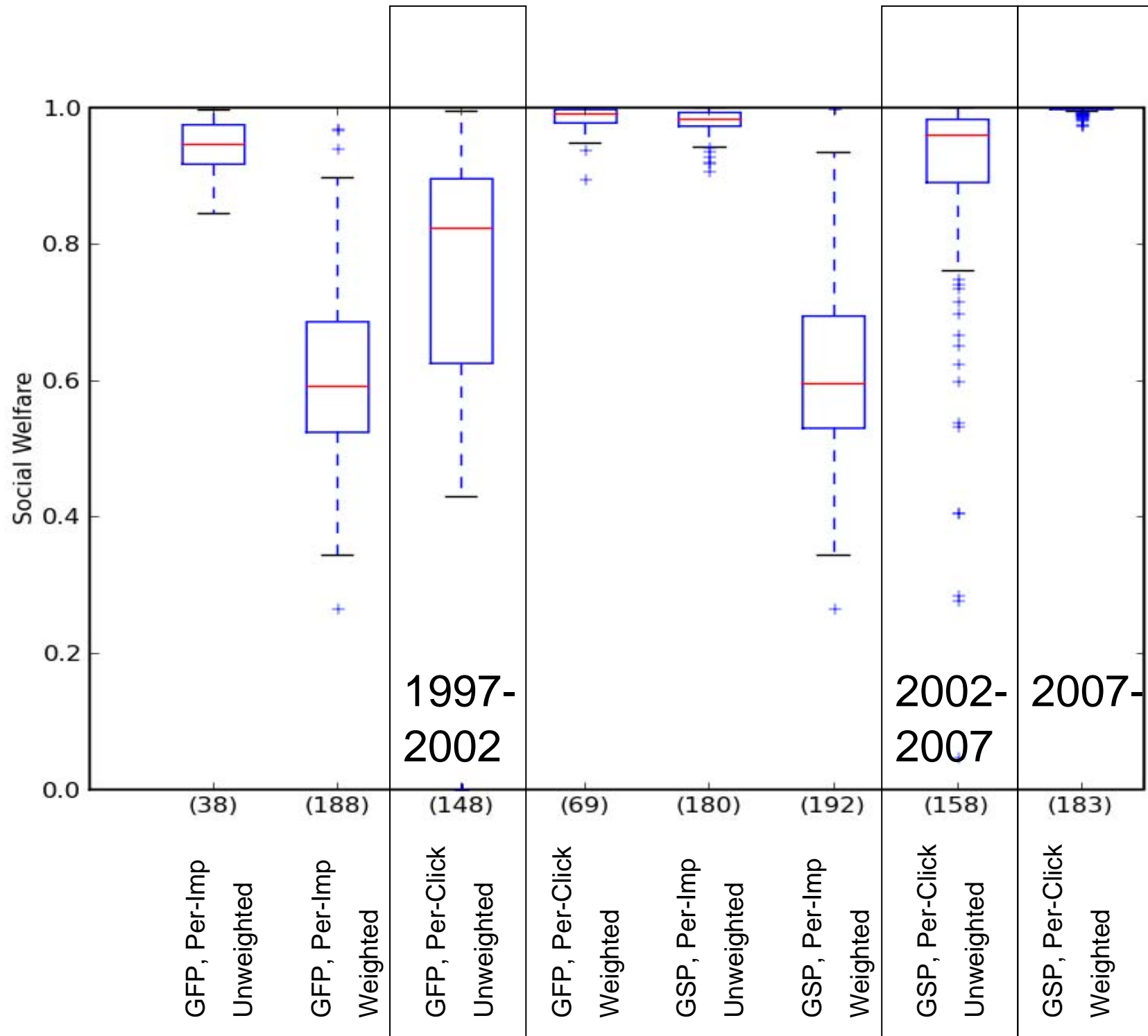




# [EOS]'s auction with [Varian]'s preference model

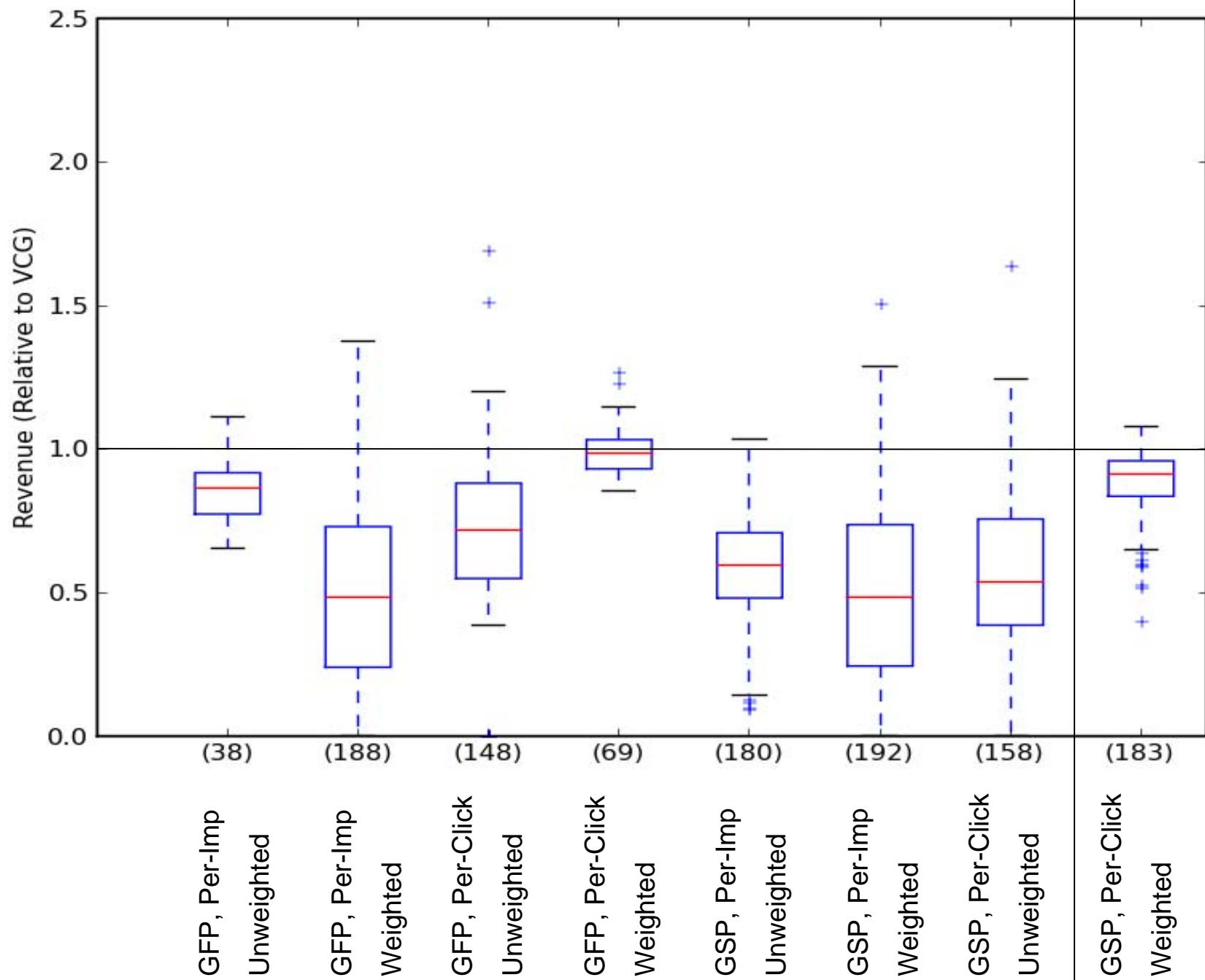


# Yahoo! Auctions: Past and Present





# [Varian]: VCG revenue is a lower bound on SNE revenue



# Multiple Equilibria of GSPs [Varian; EOS]

- Each agent can have many best responses to an equilibrium strategy profile.
  - Raising  $i$ 's bid increases  $(i-1)$ 's price, decreasing  $i$ 's envy.
- Given an envy-free NE / SNE, lowering an agent's bid may lead to an efficient, pure NE w/ sub-VCG revenue

← Lower bids

4

5

6

Higher bids →

7

8

Not Equilibrium

Nash Equilibrium

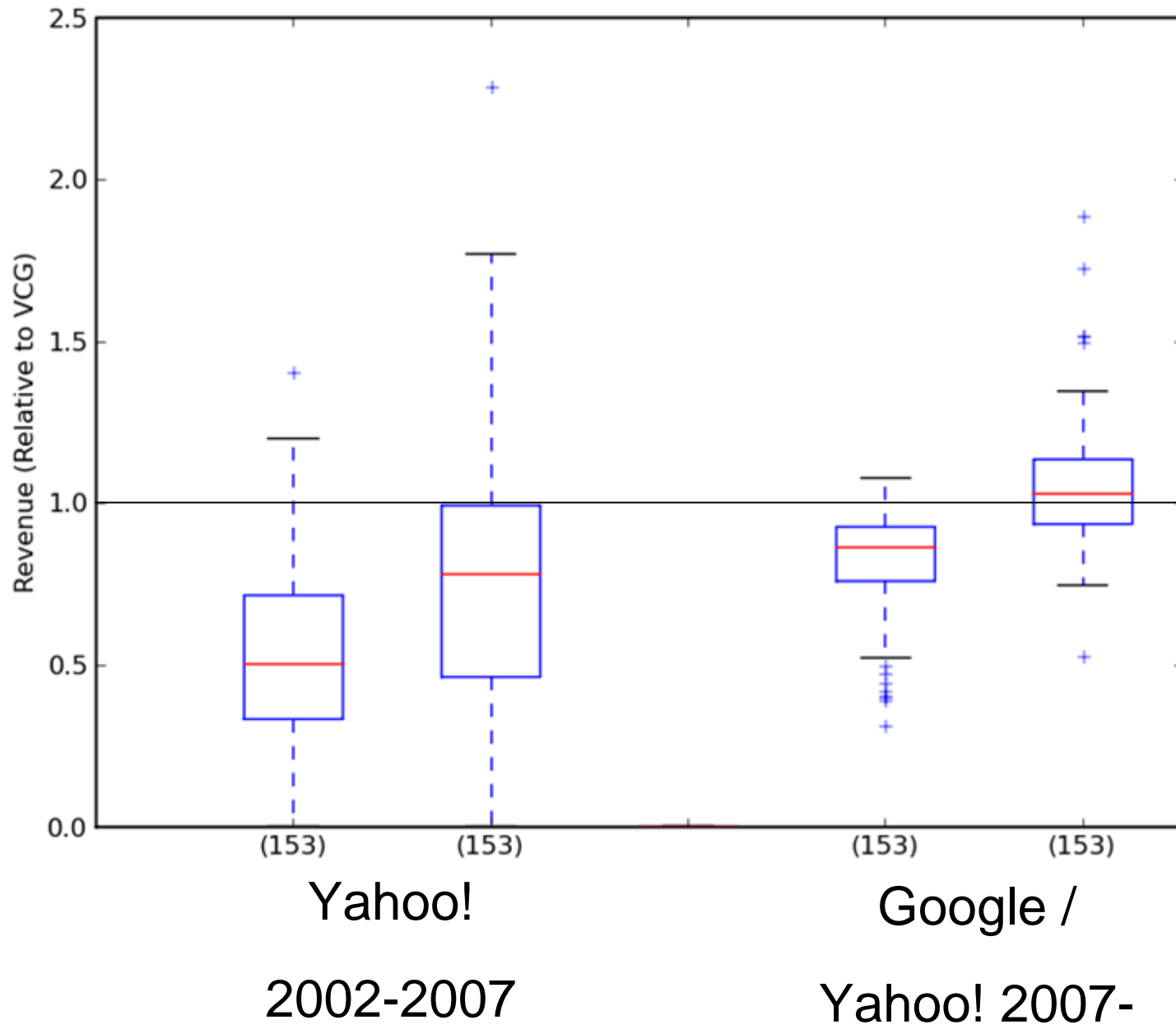
Envy-free Nash  
Equilibrium

Not Equilibrium

- Even if pure NE exist for continuous bids, they may not exist for discrete bids.

# Equilibrium selection

- Previous results simply showed the first equilibrium found by simpdiv
  - Often a mixed strategy over arbitrary points on equilibrium interval
- Local search approach to equilibrium selection:
  - Start point: Nash equilibrium found by simpdiv
  - Neighbours: *Nash equilibria* where one bid is changed by one increment
  - Objective: maximize/minimize sum of bids
  - Algorithm: Greedily raise bids (choose bidder by random permutation); random restarts.



# Summary

- Many position auctions are tractable:
  - Polynomial-size AGG
  - Polynomial-time expected utility by dynamic programming
- Very general preference model:
  - Position-specific valuations
  - Non-separable CTRs (and arbitrary weights)
- Experimental results consistent with existing theory and practice.

# Future Work

- Economic:
  - Use full preference model (learn from data)
  - Model richer preferences (e.g. cascading CTR  
[Aggarwal, et al, 2008; Kempe, Mahdian, 2008])
- Computational:
  - *In progress:* Adapt SEM [Porter, Nudelman, Shoham, 2006] to AGGs: Allows enumerating equilibria (answer questions like “what percentage of pure equilibria are envy free?”)

*Thank You.*